

Error Measurements

Let v_A be the approximate value and v_E be the exact value

- Absolute error: $|v_A - v_E|$
- Relative error: $\frac{|v_A - v_E|}{v_E}$
- Percentage error: $\frac{|v_A - v_E|}{v_E} \times 100\%$

Taylor Series

Familiar (and useful) examples of Taylor series are the following:

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots = \sum_{k=0}^{\infty} \frac{x^k}{k!} \quad (|x| < \infty) \quad (1)$$

$$\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k+1}}{(2k+1)!} \quad (|x| < \infty) \quad (2)$$

$$\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots = \sum_{k=0}^{\infty} (-1)^k \frac{x^{2k}}{(2k)!} \quad (|x| < \infty) \quad (3)$$

$$\frac{1}{1-x} = 1 + x + x^2 + x^3 + \dots = \sum_{k=0}^{\infty} x^k \quad (|x| < 1) \quad (4)$$

$$\ln(1+x) = x - \frac{x^2}{2} + \frac{x^3}{3} - \dots = \sum_{k=1}^{\infty} (-1)^{k-1} \frac{x^k}{k} \quad (-1 < x \leq 1) \quad (5)$$

Taylor Series about a point

1.2 Taylor Polynomials

One of the cornerstones of numerical analysis is Taylor's theorem about which you learned in Calculus. A short study bears repeating here, however.

Theorem 1. Suppose that $f(x)$ has $n+1$ derivatives on (a, b) , and $x_0 \in (a, b)$. Then for each $x \in (a, b)$, there exists a ξ , depending on x , lying strictly between x and x_0 such that

$$f(x) = f(x_0) + \sum_{j=1}^n \left(\frac{f^{(j)}(x_0)}{j!} (x - x_0)^j \right) + \frac{f^{(n+1)}(\xi)}{(n+1)!} (x - x_0)^{n+1}.$$

Pseudo-code for Bisection

Step 1: Set $L = f(a)$;

Step 2: Set $m = \frac{a+b}{2}$; $M = f(m)$;

Step 3: If $LM < 0$ then set $b = m$; else set $a = m$ and $L = M$;

Step 4: Go to Step 2.

False Position

$$x_r = x_u - \frac{f(x_u)(x_l - x_u)}{f(x_l) - f(x_u)}$$

Newton's Method

$$x_{i+1} = x_i - \frac{f(x_i)}{f'(x_i)}$$

Secant Method

$$x_{n+1} = x_n - g(x_n) \frac{x_n - x_{n-1}}{g(x_n) - g(x_{n-1})}$$

Trapezoid Rule

$$I = (b - a) \frac{f(a) + f(b)}{2}$$

Trapezoid Rule, Uniform Spacing

$$\int_a^b f(x) dx \approx T(f; P) = h \left\{ \sum_{i=1}^{n-1} f(x_i) + \frac{1}{2} [f(x_0) + f(x_n)] \right\}$$

Simpson's 1/3 Rule

$$I = \frac{h}{3} [f(x_0) + 4f(x_1) + f(x_2)]$$

where $h = (b - a)/2$

- The formula is

$$I \approx (b - a) \frac{f(x_0) + 4 \sum_{i=1,3,5}^{n-1} f(x_i) + 2 \sum_{j=2,4,6}^{n-2} f(x_j) + f(x_n)}{3n}$$

where $h = \frac{b-a}{n}$

Definition of Simpson's 3/8 Rule

$$I = \frac{3h}{8} [f(x_0) + 3f(x_1) + 3f(x_2) + f(x_3)]$$

where $h = (b - a)/3$

Romberg Integration

procedure Romberg(*f*, *a*, *b*, *n*, (*r_{ij}*))

real array (*r_{ij}*)_{0:n×0:n}

integer *i*, *j*, *k*, *n*

real *a*, *b*, *h*, *sum*

interface external function *f*

h* ← *b* − *a

***r*₀₀ ← (*h*/2)[*f*(*a*) + *f*(*b*)]**

for *i* = 1 to *n* do

***h* ← *h*/2**

***sum* ← 0**

for *k* = 1 to 2^{*i*} − 1 step 2 do

***sum* ← *sum* + *f*(*a* + *kh*)**

end for

***r_{i0}* ← $\frac{1}{2}r_{i-1,0} + (sum)h$**

for *j* = 1 to *i* do

***r_{ij}* ← *r_{i,j-1}* + (*r_{i,j-1}* − *r_{i-1,j-1}*)/(4^{*j*} − 1)**

end for

end for

end procedure Romberg

Gauss's Formula

- $\int_{-1}^1 f(x)dx \approx \sum_{i=1}^n w_i f(x_i)$
- Note that x_i and w_i are the points and weights of Gaussian quadrature

Gauss's Formula, arbitrary interval

- $\int_a^b f(y)dy \approx \frac{b-a}{2} \sum_{i=1}^n w_i f(y_i)$
- $y_i = \left(\frac{b-a}{2}\right) x_i + \left(\frac{b+a}{2}\right)$
- Note that x_i and w_i are the points and weights of Gaussian quadrature