

**MANE 3351**

# Lecture 9

## Classroom Management

### Agenda

- Part 2: Bisection Search Error Analysis
- False Position Method
- Review Test 1
- Lab 4
- LANL visit - I will be out of my office for most of today
  - One day extension on Lab 3

# Resources

## Handouts

- Lecture 9 Slides
- Lecture 9 Marked Slides

## Assignments

- [Homework 1 \(assigned 9/22/2025, due 9/29/2025 \(before 11:59 PM\)\)](#)
- [Homework 2 \(assigned 9/24/2025, due 10/1/2025 \(before 9:30 AM - no late submissions\)\)](#)
- [Lab 3 \(assigned 9/24/2025, due 10/1/2025 \(before 9:30 AM\)\)](#)
- Read textbook pages 41-46

# Schedule

Lecture/Lab	Date	Topic
7	9/24	Taylor Series, Homework 2 (due 10/1 - no late work), Lab 3 (due 10/1)
8	9/29	Roots of Equations, bisection method (not on Test 1)
9	10/1	Bisection Method Error Analysis, False Position (not on Test 1)
10	10/6	Test 1 (lectures 1-7)

8:15  
1h regular classroom

# Bisection Method: Error Analysis

## Bisection Method Theorem

Cheney and Kincaid (2004)[<sup>1</sup>] provide a definition of the bisection method

If the bisection algorithm is applied to a continuous function on an interval  $[a, b]$ , where  $f(a)f(b) < 0$ , then, after  $n$  steps, an approximate root will have been computed with error at most  $(b - a)/2^{n+1}$ .

This definition provides the following useful results:

- $|e_n| \leq \frac{1}{2^{n+1}} (b - a)$
- $n > \frac{\log(b-a) - \log 2\varepsilon}{\log 2}$

## Percent Relative Error

Chapra and Canale (2015) [^2] provide a formula for the approximate percent relative error

$$\epsilon_a = \left| \frac{x_r^{new} - x_r^{old}}{x_r^{new}} \right| \times 100\% \text{ where } x_r^{new} \text{ is the root for the present iteration and } x_r^{old} \text{ is the root from the previous iteration}$$

# Bracketing Method

$[l, u]$

## False Position

- Attempts to converge faster than bisection method by using functional information
- The new root is found by

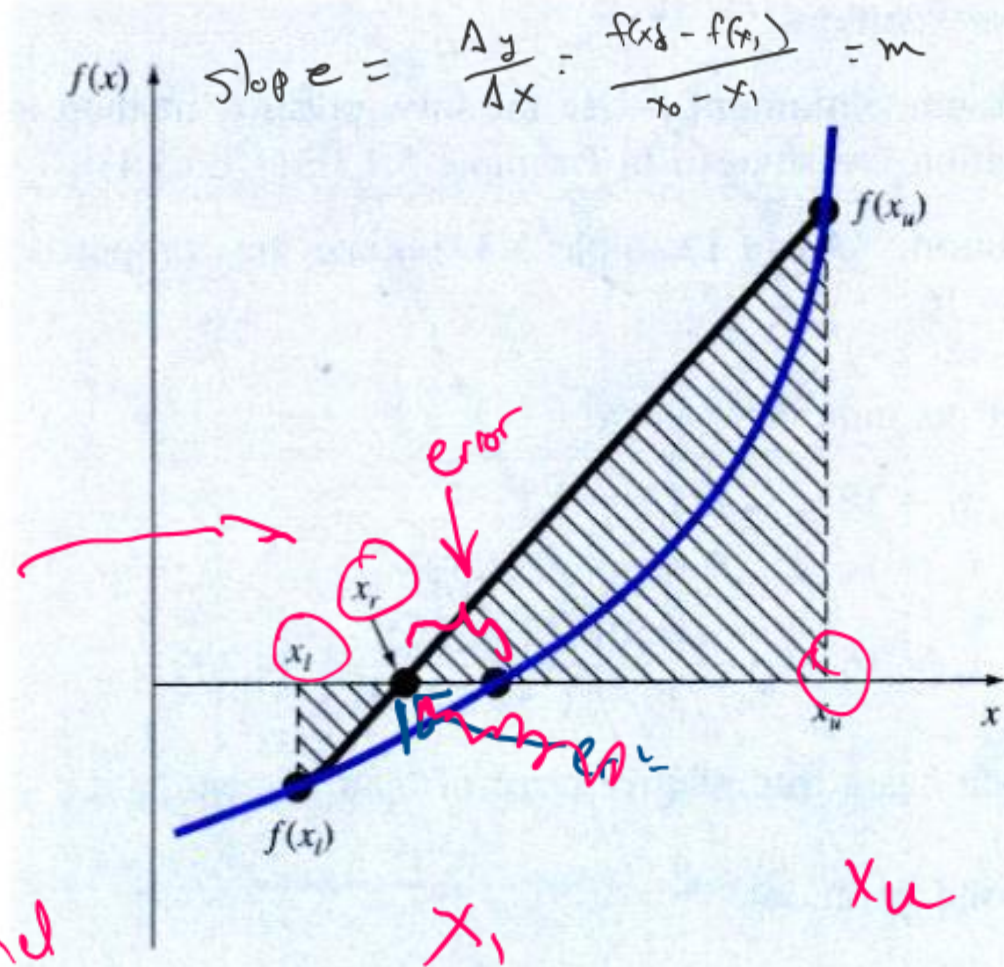
$$x_r = x_u - \frac{f(x_u)(x_l - x_u)}{f(x_l) - f(x_u)} = x_u - \frac{f(x_u)}{m}$$

- Figure 5.12 (Chapra and Canale(2015)[<sup>2</sup>]  
illustrates the false position method False Position  
Method



**FIGURE 5.12**

A graphical depiction of the method of false position. Similar triangles used to derive the formula for the method are shaded.



estimated  
root

1st  
iteration

$x_1$

$x_u$

## **False Position Code**

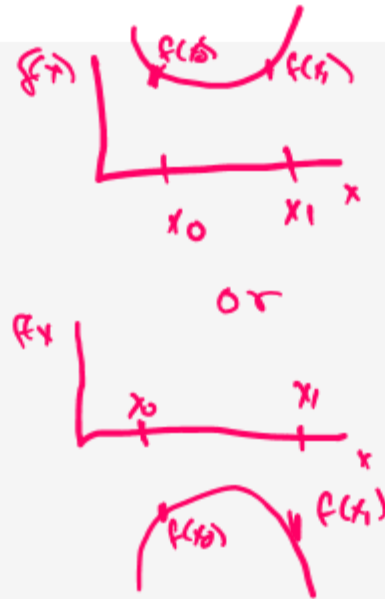
The pseudocode, shown below was taken from  
[<sup>3</sup>]

## Complete Pseudocode for Regula Falsi or False Position Method

```
1. Start
2. Define function f(x)
3. Input
   a. Lower and Upper guesses x0 and x1
   b. tolerable error e
4. If f(x0)*f(x1) > 0
   print "Incorrect initial guesses"
   goto 3
End If
5. Do
   
$$x_2 = x_0 - ((x_0 - x_1) * f(x_0)) / (f(x_0) - f(x_1))$$

   If f(x0)*f(x2) < 0
     x1 = x2
   Else
     x0 = x2
   End If
   While abs(f(x2)) > e
     
$$x_2 = x_0 - ((x_0 - x_1) * f(x_0)) / (f(x_0) - f(x_1))$$

   End While
6. Print root as x2
7. Stop
```

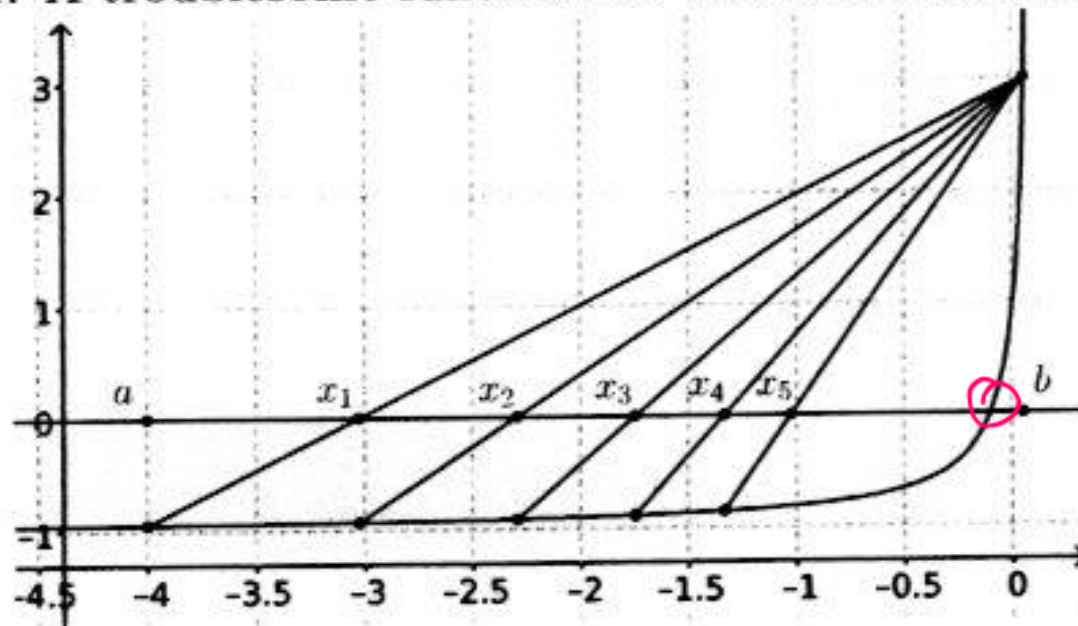


False Position Pseudocode

## False Position Error Analysis

- Much harder to analyze than bisection method
- Convergence to root depends on shape of  $f(x)$
- At times, false position may converge slowly!,  
Example from textbook<sup>[4]</sup>, shown below

Figure 2.7.1: A troublesome function for the bracketed secant method.



False Position troublesome function

# Loops in Python

- Python only supports two types of loops: for and while
- Pseudocode used do/while loop

## Python Code for False Position

```
# False Position
from scipy import stats
import math
def f(x):
    return stats.norm.cdf(x) - .25
# input a & b
while True:
    a=float(input("enter the lower bound: "))
    b=float(input("enter the upper bound: "))
    if f(a)*f(b)<0.0:
        break
    print("incorrect bounds, please re-enter")
print("the lower bound is {}".format(a))
print("the upper bound is {}".format(b))
counter=0
# process loop
while True:
    m= a - ((a-b)*f(a)) / (f(a)-f(b))
    if f(a)*f(b)<0.0:
        b=m
    else:
        a=m
    counter=counter+1
    if math.fabs(f(m)) <0.0005:
        break
print("the root is {}".format(m))
print("the value at the root is {}".format(f(m)))
print("the number of steps were {}".format(counter))
```

entering a & b  
& checking that  
root is bracketed

start  
→

end  
→

not in the while loop

## Test One

- You are allowed one 4 inch by 6 inch notecard containing handwritten notes
- Calculator is needed; no programmable calculators that can calculate derivatives
- Covers material from Lectures 1 - 7
- Review Homework 1 and 2 and solutions
- Review Test 1
- Resistor information will be provided

outside  
my office (shelf)

front & back



2. (24 points) **Error Analysis**

Question 2 analyzes the effectiveness of a third-order Taylor series polynomial used to approximate  $f(x) = 2\sin(3x)$ . The Taylor series approximation is  $T_3(x) = 6x - 9x^3$ . Make sure that your calculator is set to radians and not degrees when working this problem.

(a) (8 points) What is the value of the absolute error for  $f(1)$ ?

(b) (8 points) What is the value of the relative error for  $f(1)$ ?

what is needed  
to calculate  
any error?

$f(x)$  1. exact value  
 $T_3$  2. Approximate  
value

Full '24  $\rightarrow$  sin

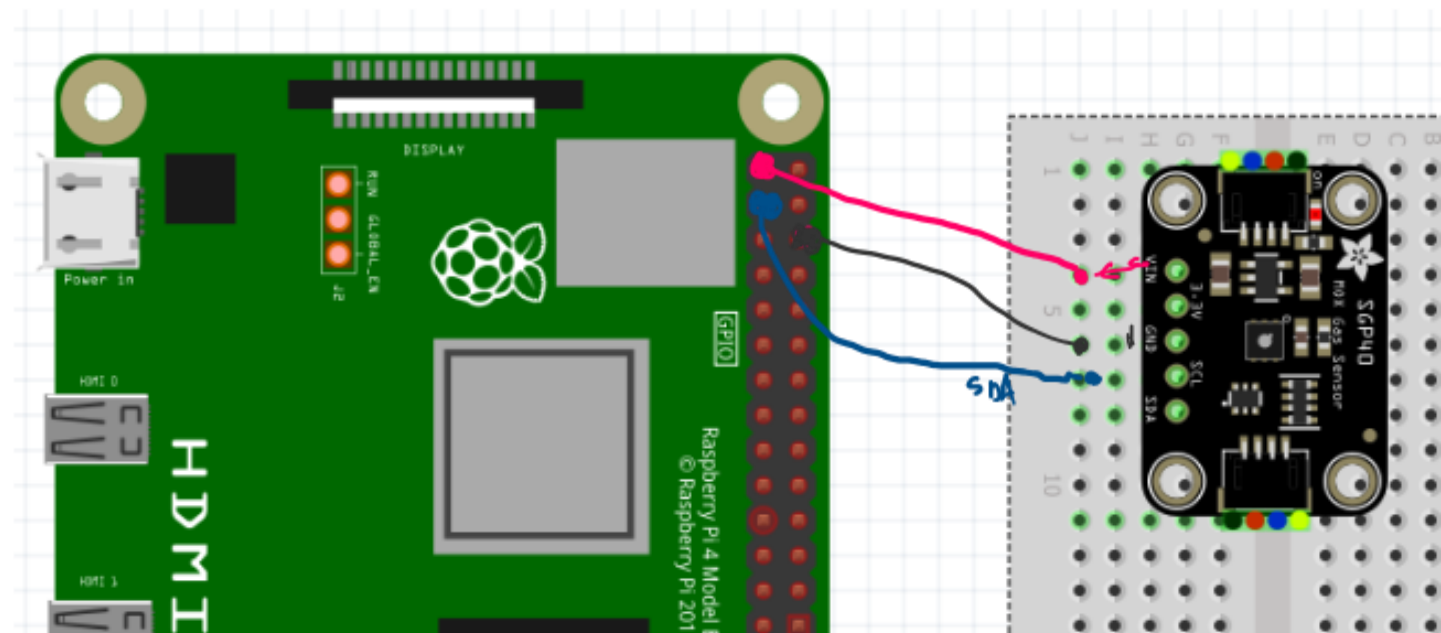
$$f(x) = 4 \cos(.5x)$$

$f(x) \rightarrow 5^{\text{th}}$  order polynomial

derivative  $f(x) = 4e^{5x}$

Raspberry Pi	SGP40
3.3V	VIN
GND	GND
GPIO 2	SDA
GPIO 3	SCL

The details of the SGP40 may be hard to read. The pin names are SCL, and SDA from top to bottom.



## References

[1]: Cheney, W. and Kincaid, D. (2004), *Numerical Mathematics and Computing*, 5th edition

[2]: Chapra, S. and Canale, R. (2015), *Numerical Methods for Engineering*, 7th edition

[4]: Brin, L., (2020), *Tea Time Numerical Analysis: Experiences in Mathematics*, 3rd edition